

Projecting Maps into the Future: Spatially Explicit Agent-Based Simulation

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Simulation and Geographic Information – a win-win situation

Realistic information for scenario building and initialization

Mapping dynamic aspects; making usage of maps in a decision making context



Simulation and Geographic Information

- Simulation systems offer interfaces for importing geographic data in different formats
 - → supported by libraries for handling spatial information (e.g. GeoTools)
 - \rightarrow traffic simulation (vehicles, pedestrian, shipping, ...)
- GIS systems offer interfaces for program code implementing simulations
 - \rightarrow next step beyond spatial analytics
- Modularization of elements → build integrated systems using a simulator, spatial analytics from GIS, VR visualization...



Simulation Approaches

Many different forms have been used together with GIS

- System dynamics
- Micro simulation (economy, sociology, demography, traffic...)
- Individual-based models (biology, ecology)
- **Object-oriented simulation** (computer science, engineering)
- \rightarrow Agent-based Modelling and Simulation

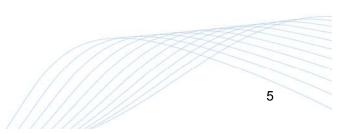




Outline

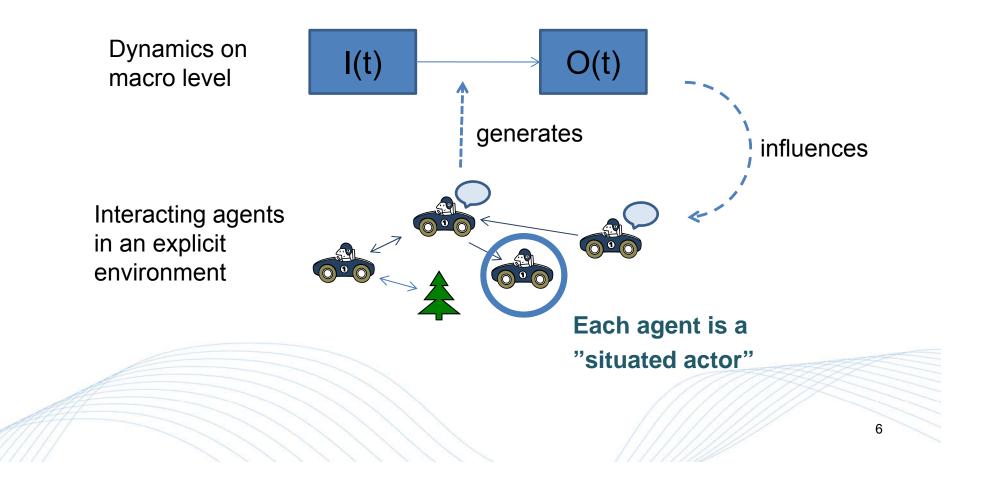
- Agent-Based Simulation
- Role and Properties of Environmental Model
- Two Examples
- SeSAm as a tool for Agent-Based Simulation
- Conclusion







Agent-Based Simulation





Environmental Model

- Part of the Model ↔ Infrastructure for Simulation
- Resembles the real world/original system environment in sufficient detail
- \rightarrow Substrate for locality of entities
- \rightarrow Ground for stigmergic interaction
- → External memory
 - In the same way as in the original system
 - Abstraction for reasoning within the agents





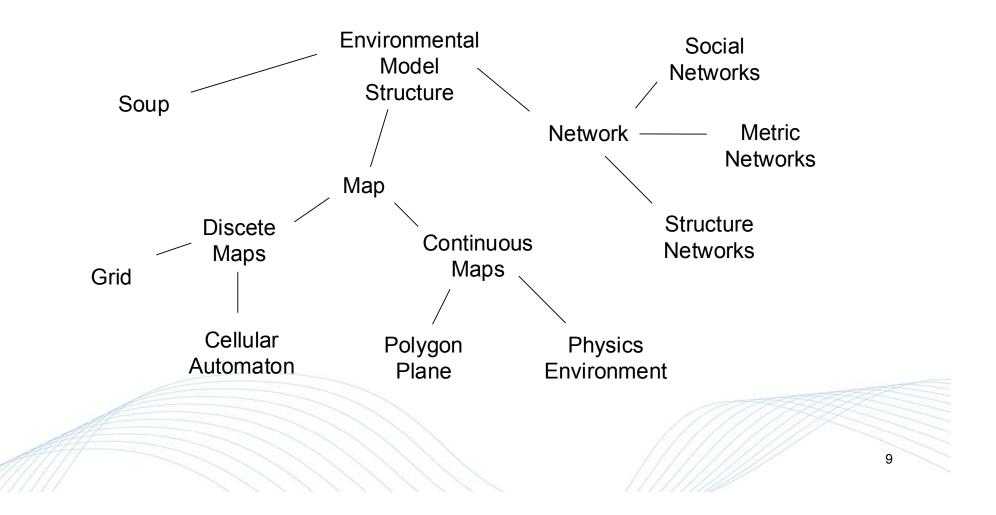
Agents interact with their environment

- Movement of entities
- Modifying shapes
- Generation of entities
- Deletion of entities
- Modifying properties
- → Simulate effect of (many) (local) decision makers on space
- → Range of decision makers from authorities to consumers, from road operators to travelers
- → Different perspectives, indirect and direct effect



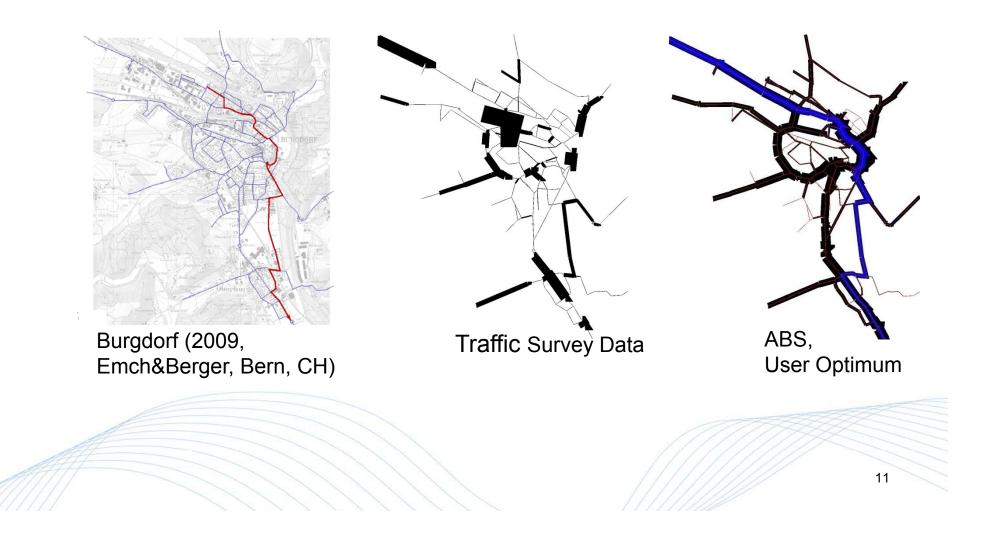


Spatial Representations for Environmental Models





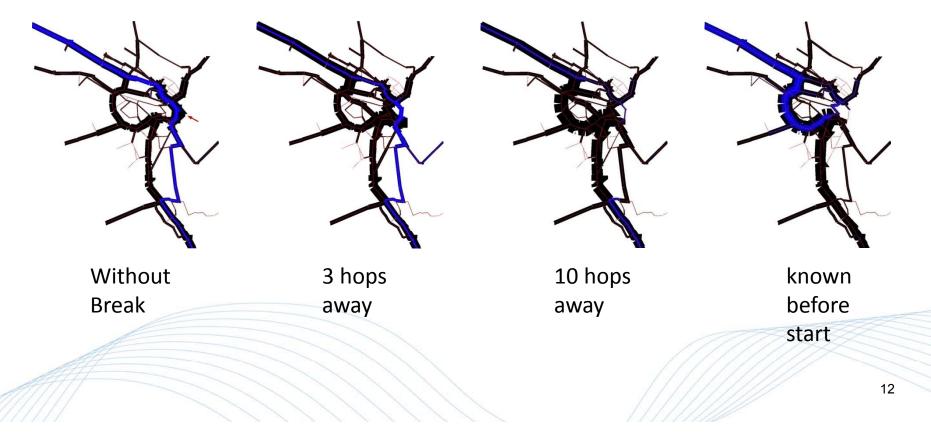
Example in Traffic





With ABS we can answer...

What if, a link is broken and travelers are informed in different distances?





Another Example

What happens directly after an earthquake in a populated area?
 → what if all bridges and over/underpasses in Örebro are destroyed in a large-scale emergency situation



A kind of showcase for combination of advanced map information and complex agent-based simulation



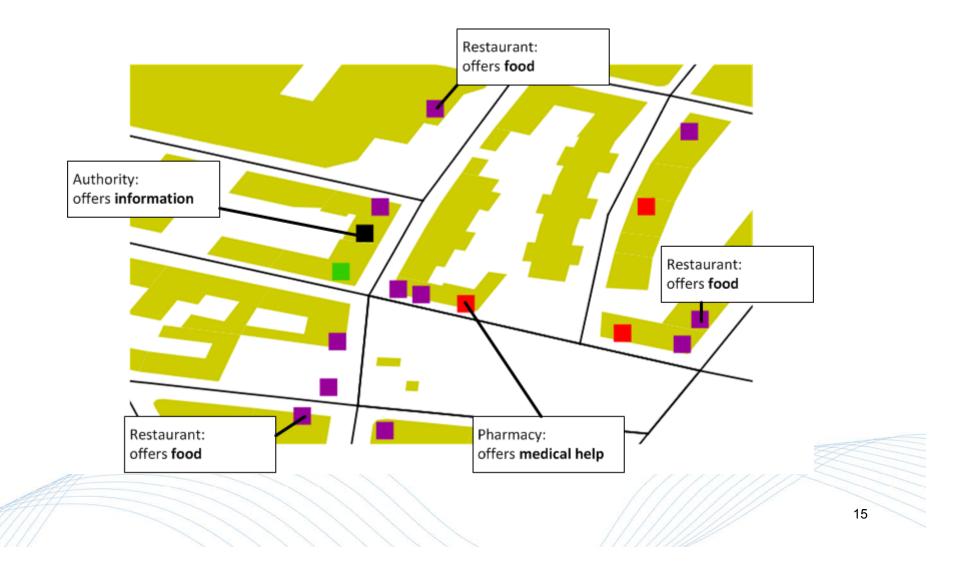
Agents

- ... have **needs** to satisfy (hunger, medical help, safety, information)
- ... want to find **places** where these needs can be fulfilled
- ... in stead of just using the object class, we add an additional **information layer with affordances**:
- ... agents **plan route** to selected object using their mental map
- ... update map if it discovers inconsistencies or if another person informs about changes
- ... if new information \rightarrow feasiliby of path is checked and updated



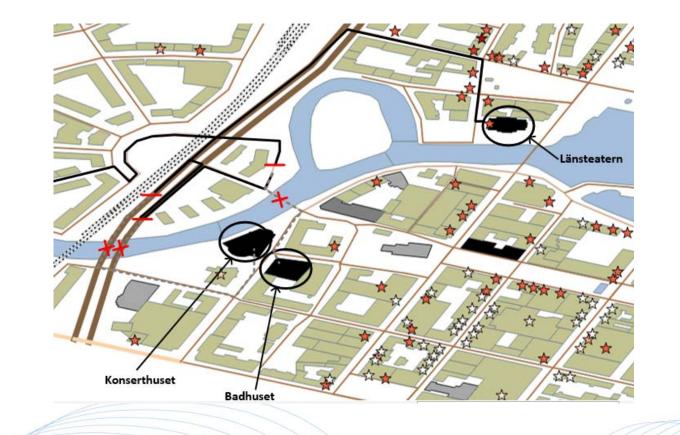


Environmental Model





Trajectory produced by agents' reasoning





SeSAm

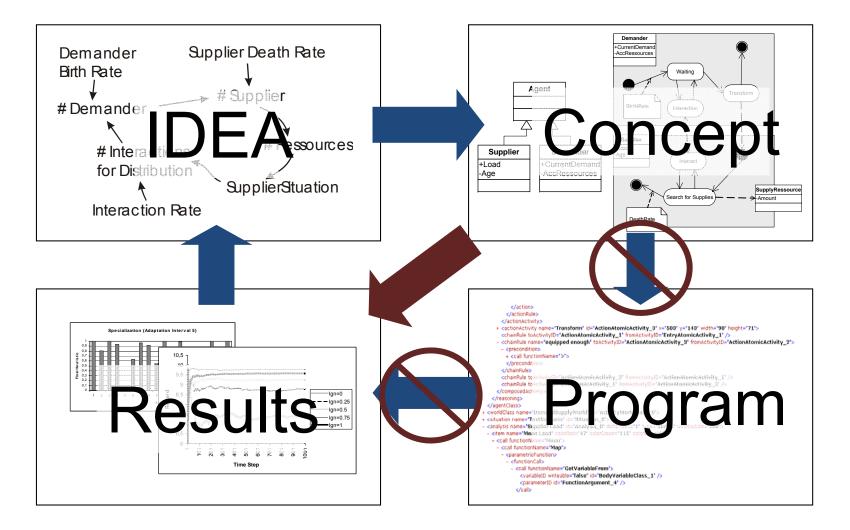
- Shell for Simulated MultiAgent Systems
- Vision: Providing a tool so that multiagent simulation is accessible to people without training in formal programming languages
- Idea: Combine the a high-level declarative language for describing the simulation model with powerful visual programming
- Import/Export Shape-Files and OSM-Files
- \rightarrow Rapid Prototyping for Experts
- \rightarrow Easy Development for Novices

www.simsesam.org



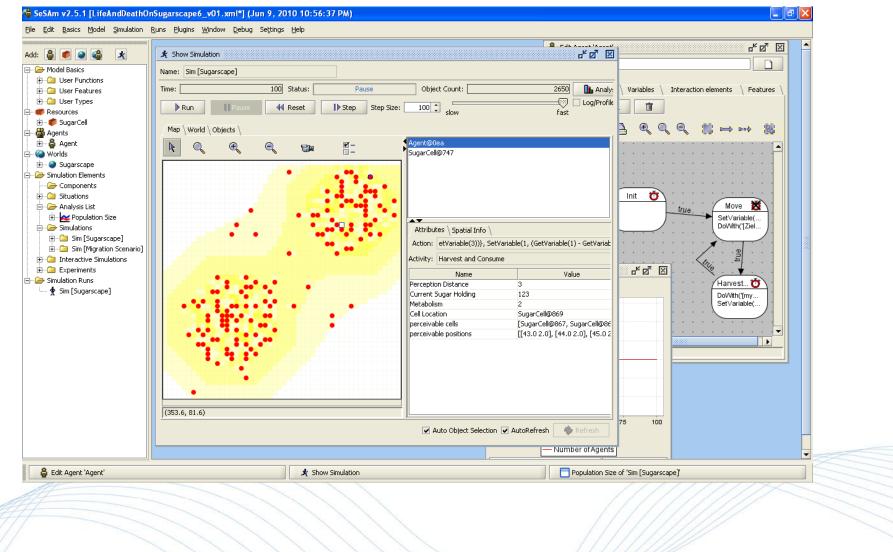


SeSAm in the Process





How it looks like...





Summing Up

- Agent-based Simulation with environmental models
 using geographic information
- It is feasible, useful and has great potential
- Variety of tools are available for users with different expertise

Future?

- \rightarrow More applications with more elaborate map data
- \rightarrow Virtual Reality for Interaction with Users
- \rightarrow Integration of sensors