



SOKIGO

ADDNODE GROUP

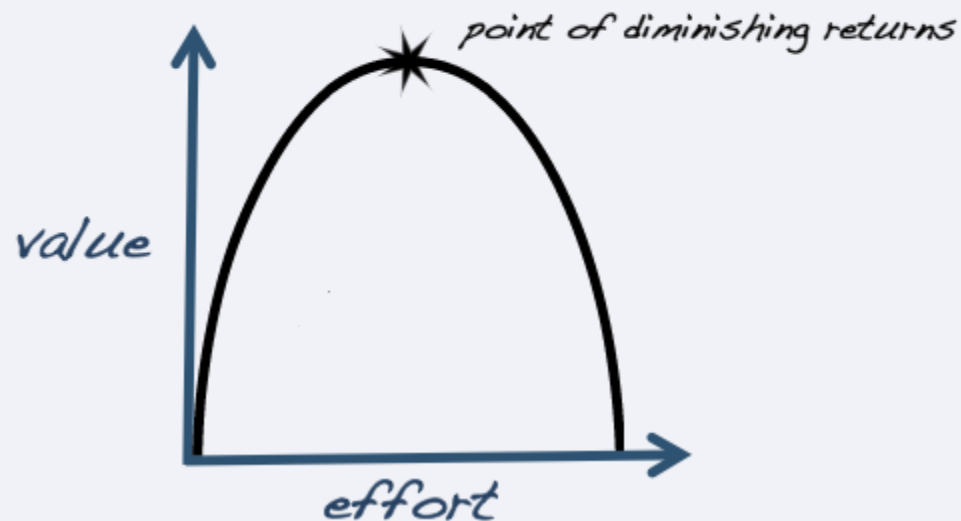
DECERNO

ADDNODE GROUP

HUR NYA TEKNIKER HJÄLPER VERKSAMHETEN

Abel González & Lukas Bergliden

“GOOD ENOUGH”



Kostnad, Pris, Uppdateringsfrekvens, Precision, Upplösning



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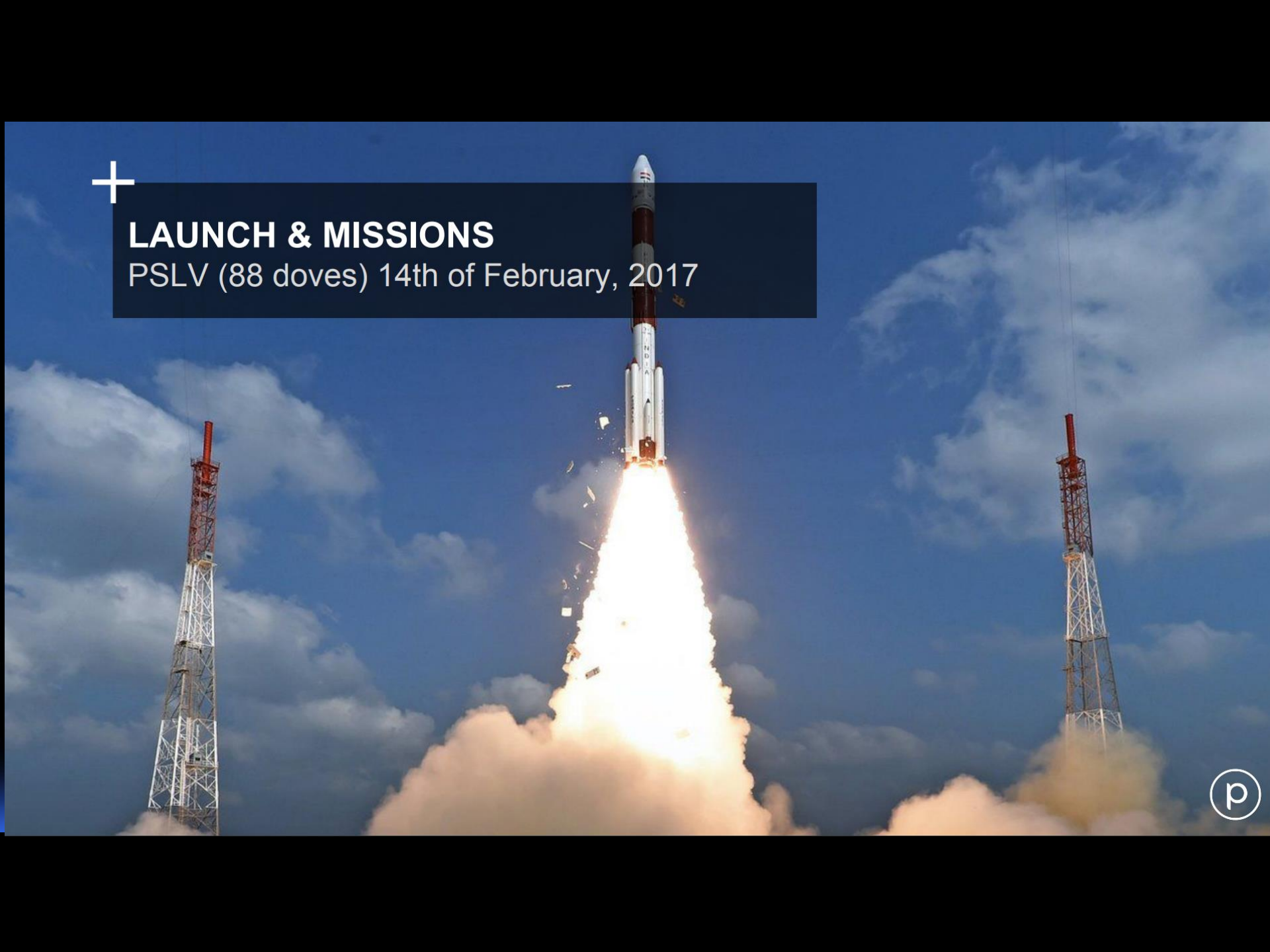
by
Igal





LAUNCH & MISSIONS

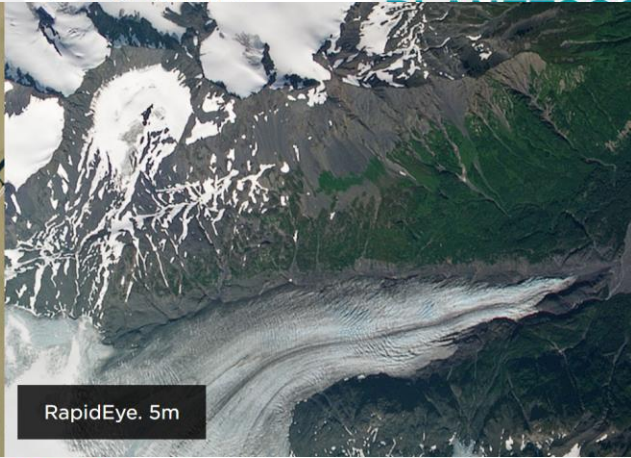
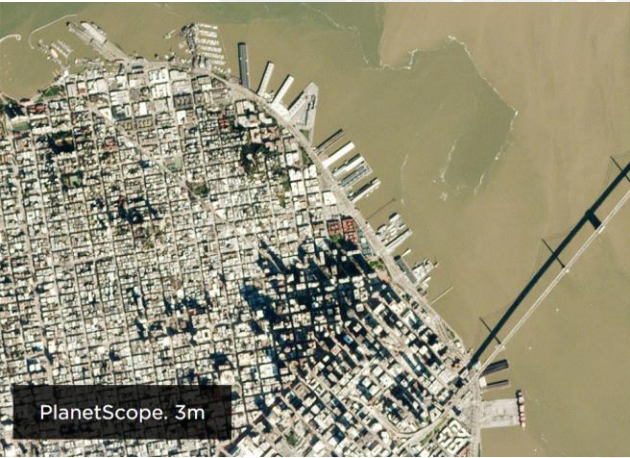
PSLV (88 doves) 14th of February, 2017





PLANET IMAGERY

4-Band RGB & NIR
3.5m



5-Band RGB, NIR & Red Edge
6.5m

RAPIDEYE



DECERNO

BUILD 13

Build 13 is Planet's most advanced satellite. It employs a 2nd-generation custom telescope, 29 megapixel camera, and star tracker. Together, these enhancements resulted in a greatly increased field-of-view and better edge-to-edge sharpness. In addition, a field programmable gate array processes data onboard, allowing the high throughput necessary for collecting near infrared data.

FEB



19

2015



NOV



5

2016



4

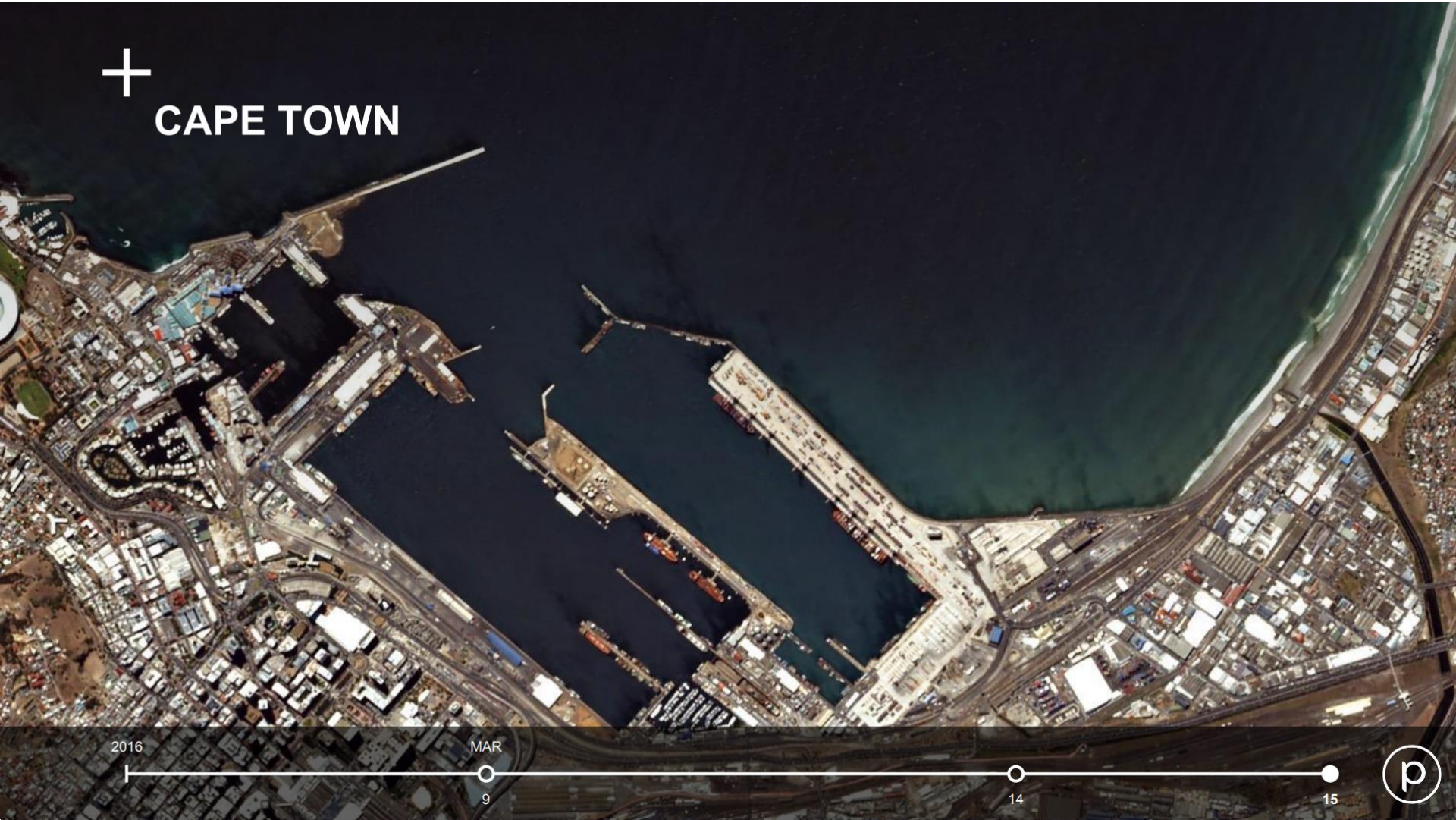
SEP



4



+
CAPE TOWN





SAN GABRIEL WILDFIRES

San Gabriel Mountains

Fire retardant lines are in red

2016

JUN

4

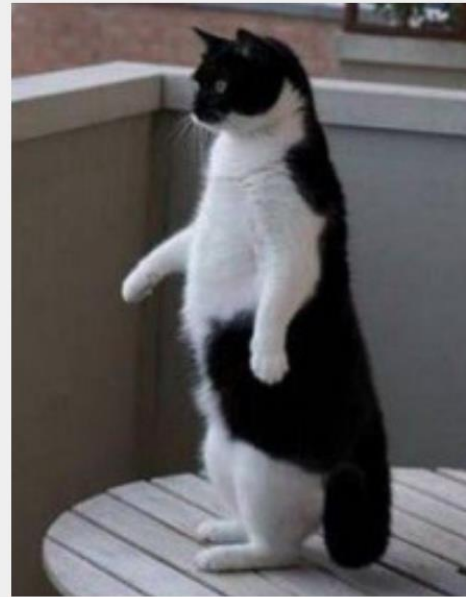
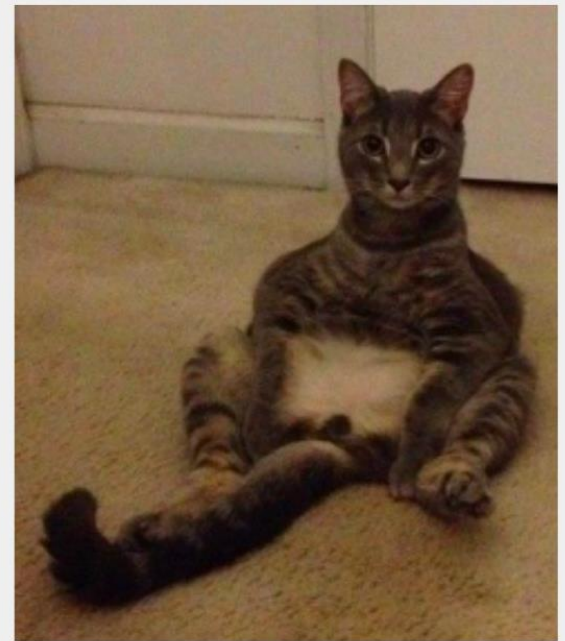
22



DECERNO

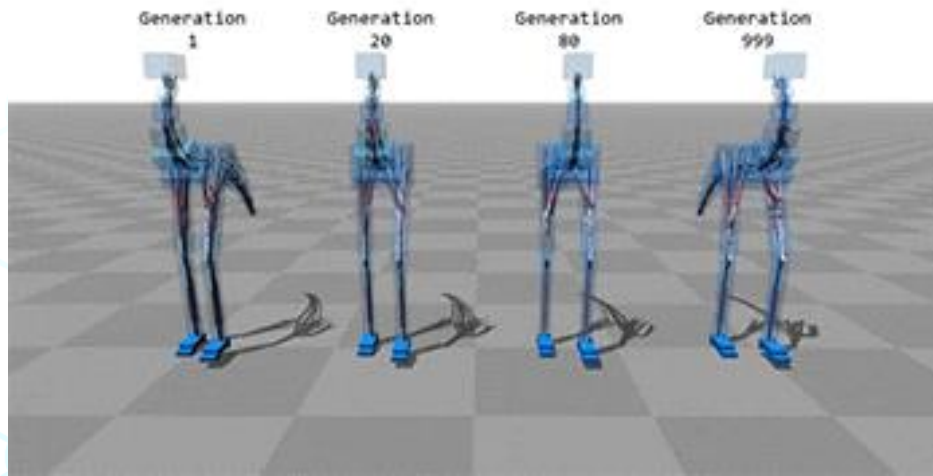
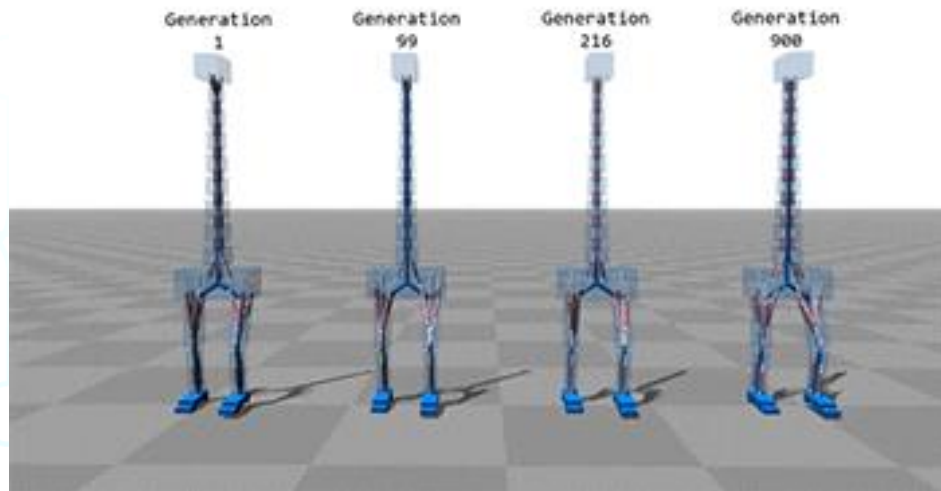
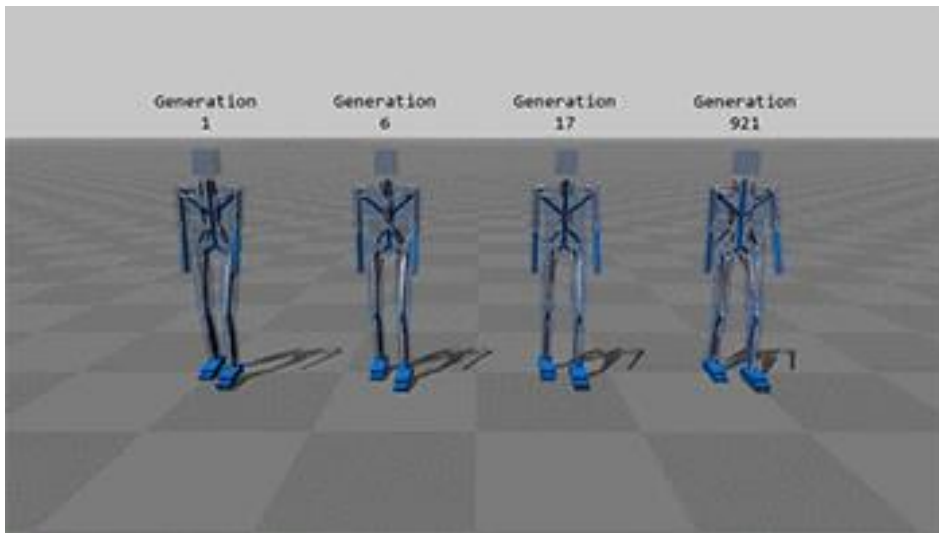
ADDNODE GROUP

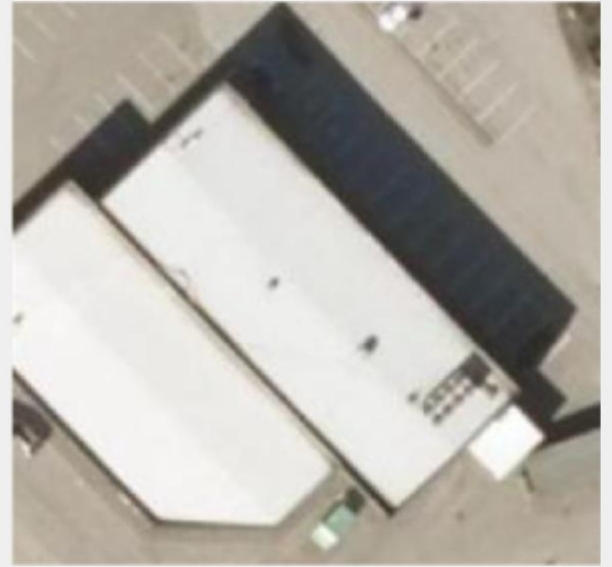


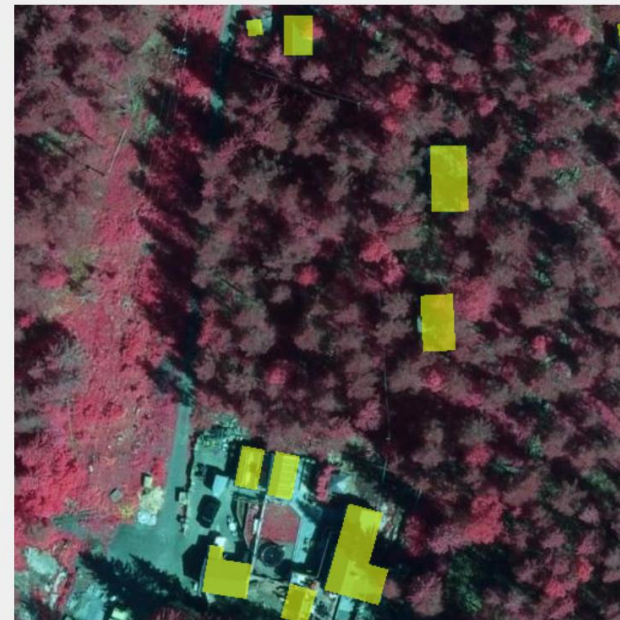
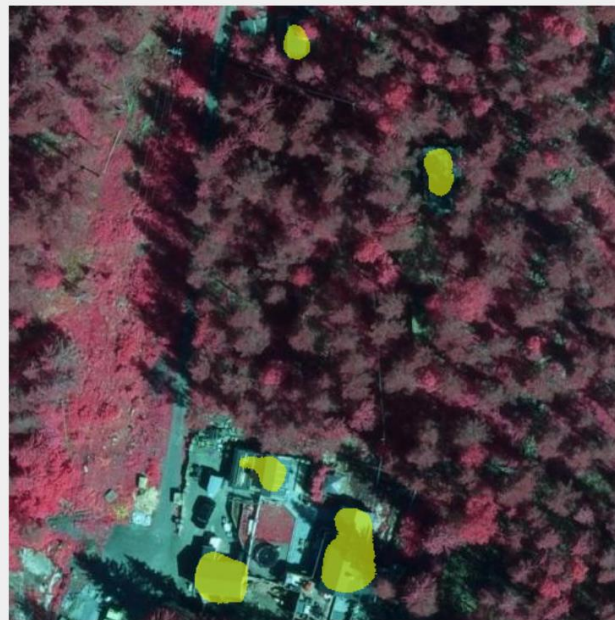


DECERNO

ADDNODE GROUP





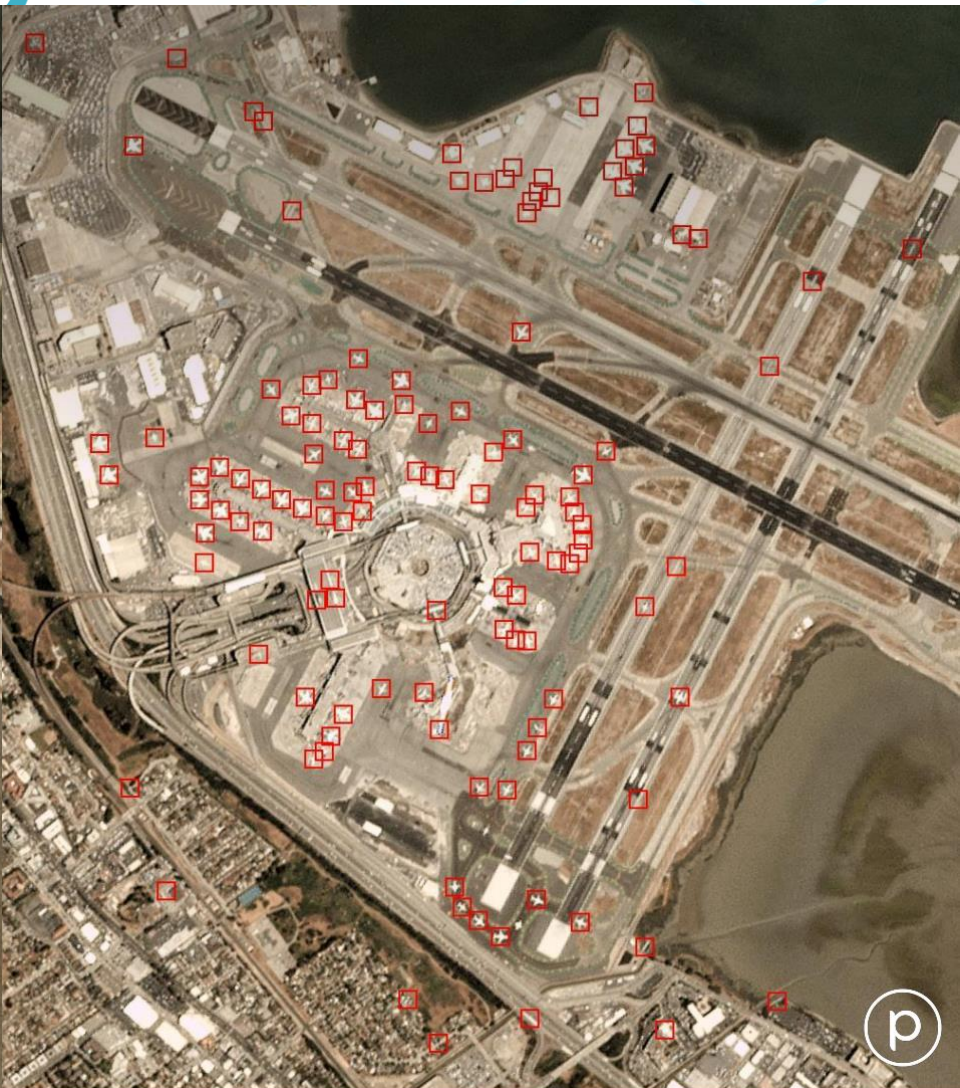


DECFERNO



PLANESNET

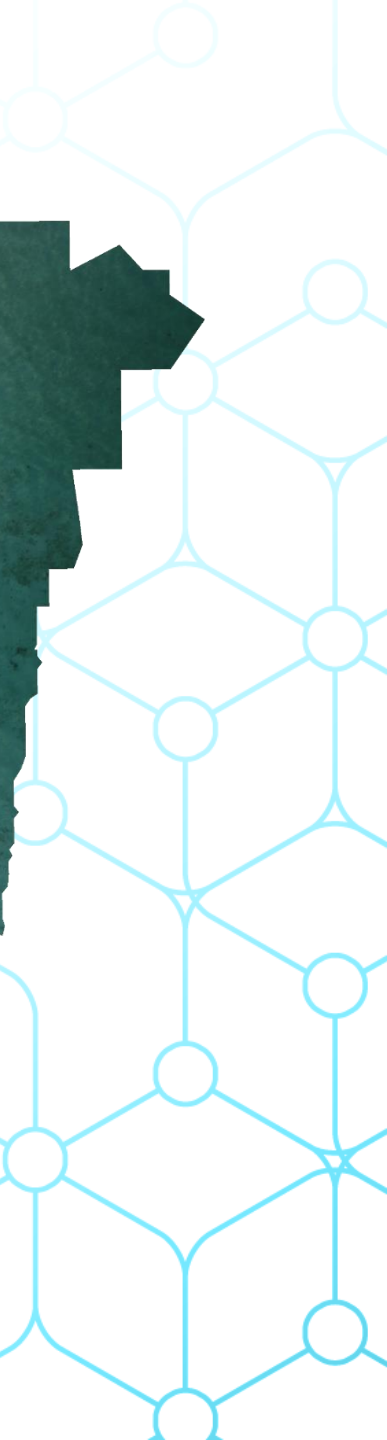
<https://github.com/rharmell/planesnet-detector>

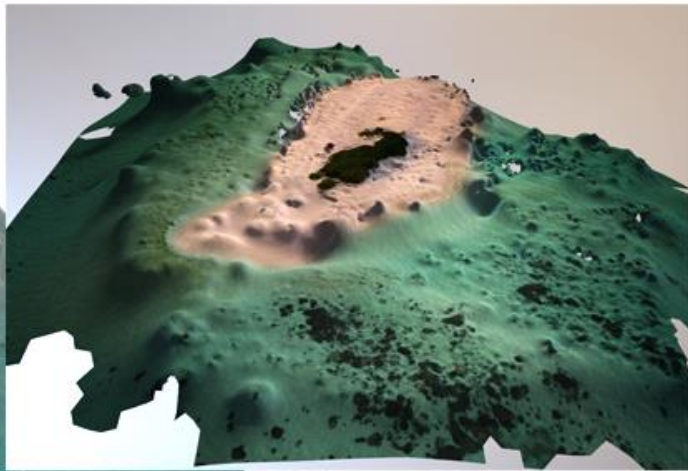




DEC

ADDNODE C







Not connected MODE N/A

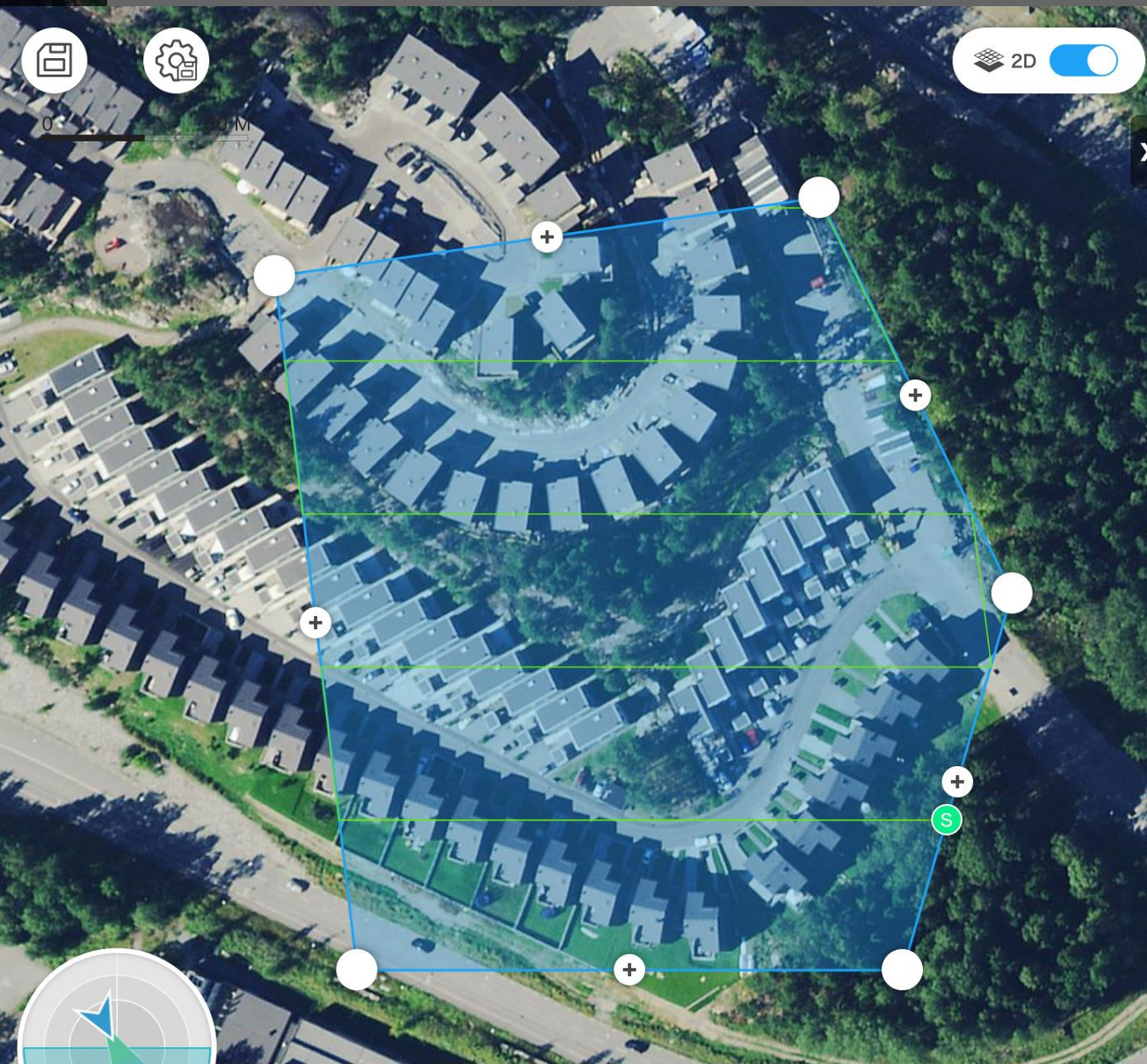


No Camera



N/A

39%



Mission 3

Waypoints Qty. 99 PTS	Flight Length 1032 M
MainPath No. 5 Lines	Cover Area 2.71 HA

Basic Advanced

Camera Model Zenmuse X5 90mm >

Shooting Angle Parallel to Main Path >

Capture Mode Hover&Capture at Point >

Flight Course Mode Inside Mode >

Speed 5.0 M/S

Altitude 241.2 M Resolution **2,0 CM/PX**

LAT

LON



Speed
N/A M/S

WGS
LAT: N/A
LON: N/A

Altitude
N/A M



Legal





Not connected MODE N/A



No Camera

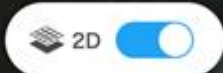


N/A

45%



75 M



Mission 4

Flight Time est.
13 MIN 4 SEC

Photos est.
75

Batteries
1 SETS approx.

Capture Interval
F: 35.1 M / S: 35.5 M

Basic

Advanced

Camera Model Zenmuse X5 15mm >

Flight Course Mode Circle Mode >

Capture Mode Hover&Capture at Point >

Speed 5.0 M/S

Flight Rad. 129.0 M Resolution 1,6 CM/PX

Building Radius 26.7 M

LAT 59.383616



Speed
N/A M/S

LAT: N/A
LON: N/A

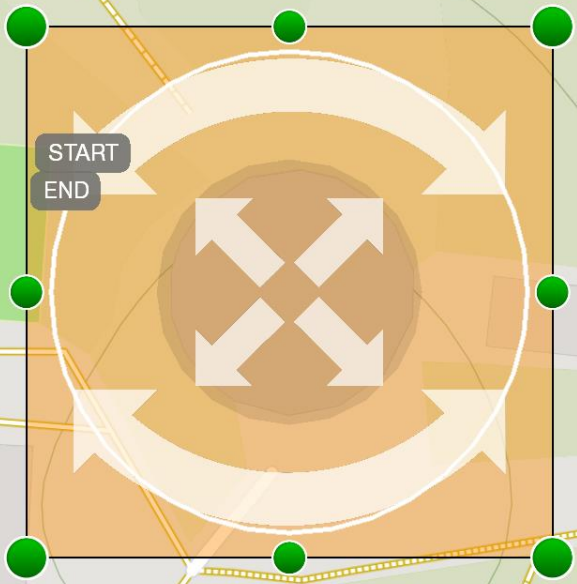
Altitude
N/A M





GSD
1.74
cm/px

51
50
49
m

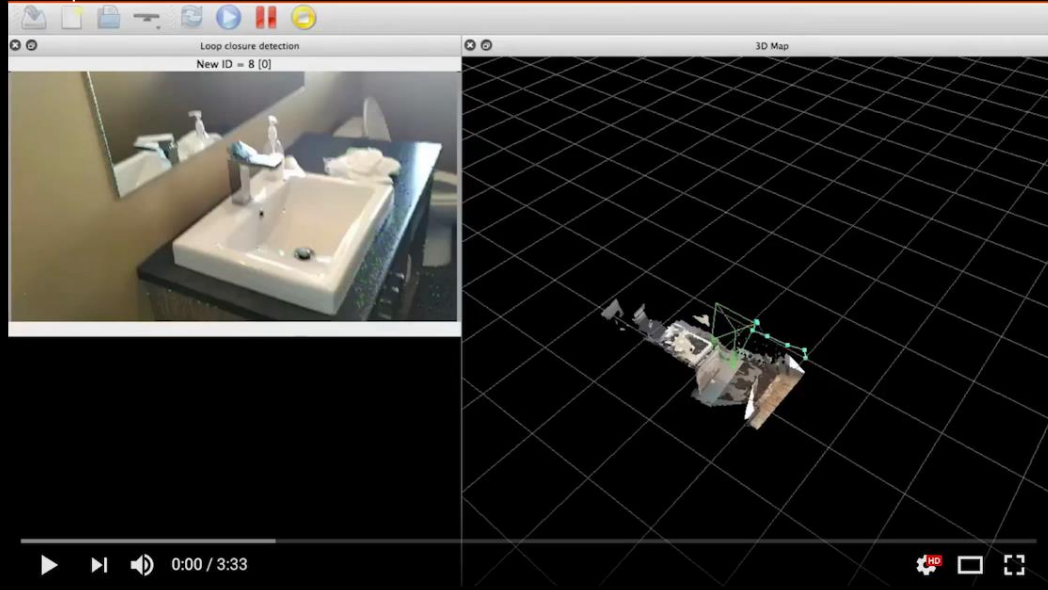


0%

105 x 106 m
5 min : 8 s

Björnstigen





Tango



Tango



ARCore



MAP

Home

How MAP Works

Research

Team

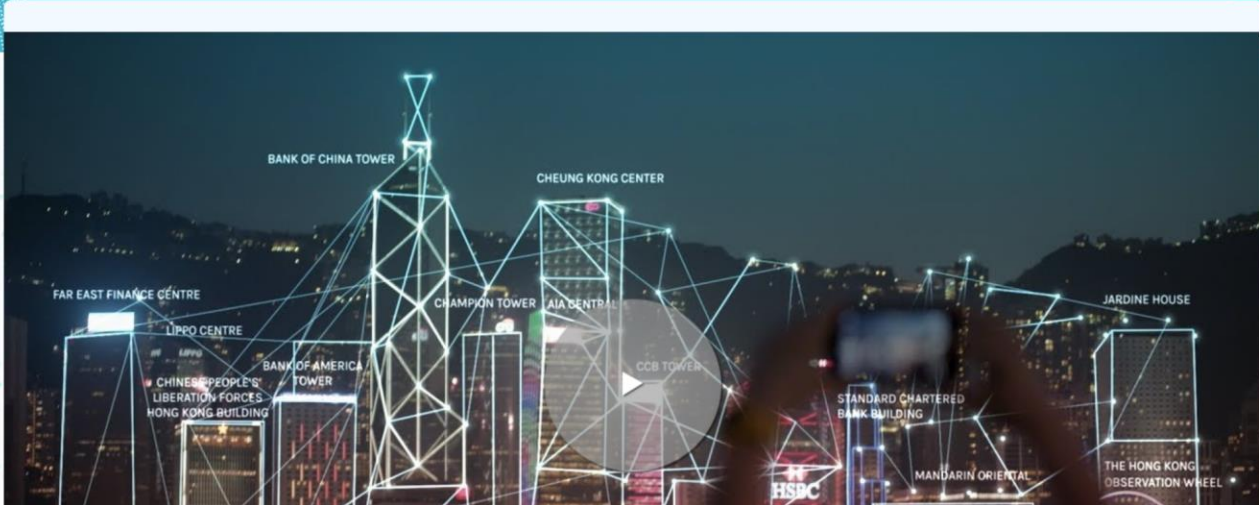
News

FAQ

SIGN UP

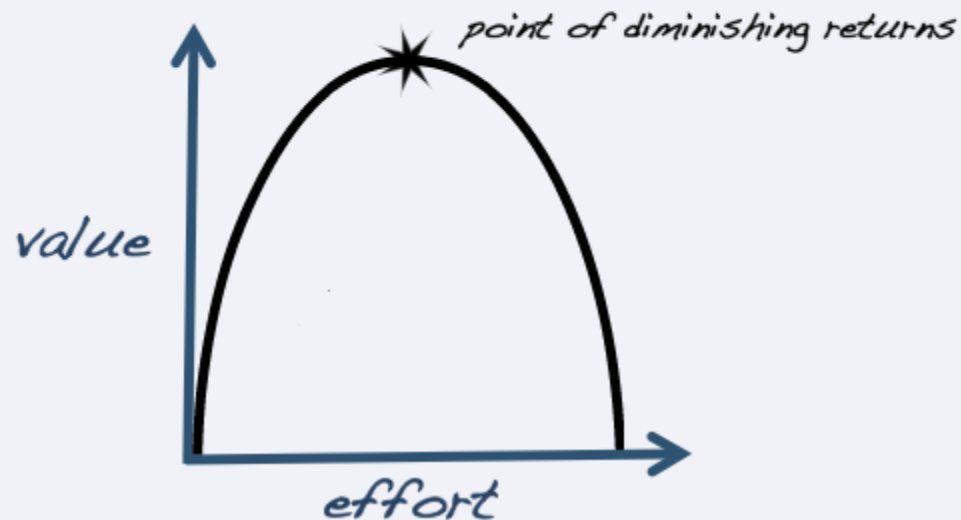


A DECENTRALIZED 3D MAPPING PROTOCOL



Hur svårt är det?

“GOOD ENOUGH”



Kostnad, Pris, Uppdateringsfrekvens, Precision,
Upplösning

I vilka tillämpningar kan det vara good enough?

? || !

